

Figure 1: Translation Errors

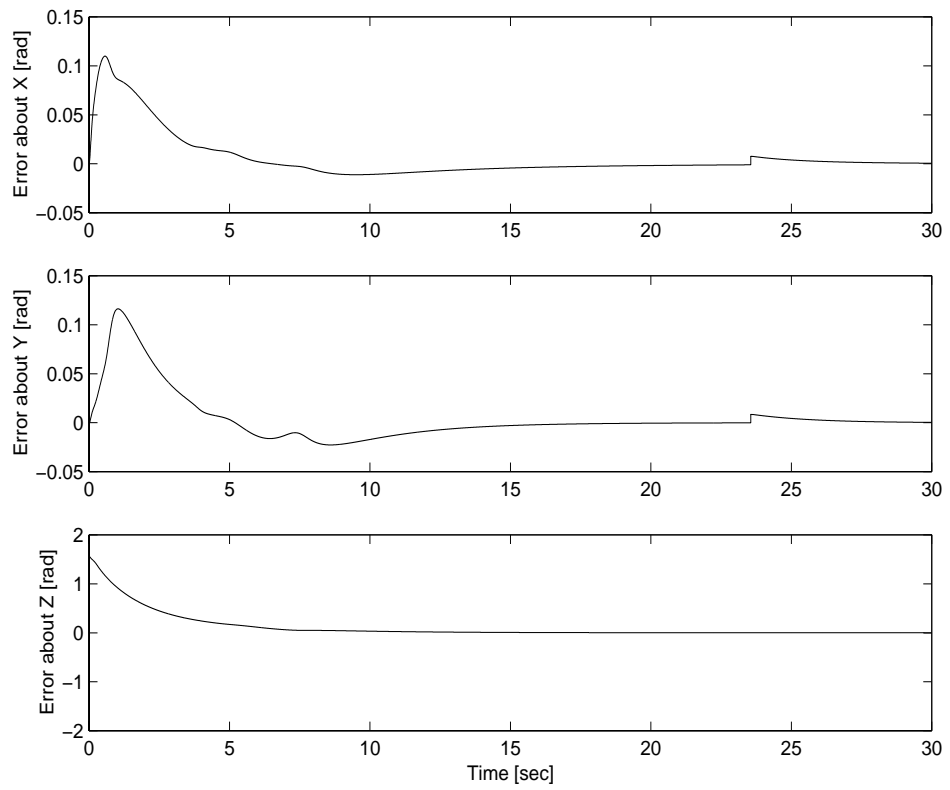


Figure 2: Rotation Errors

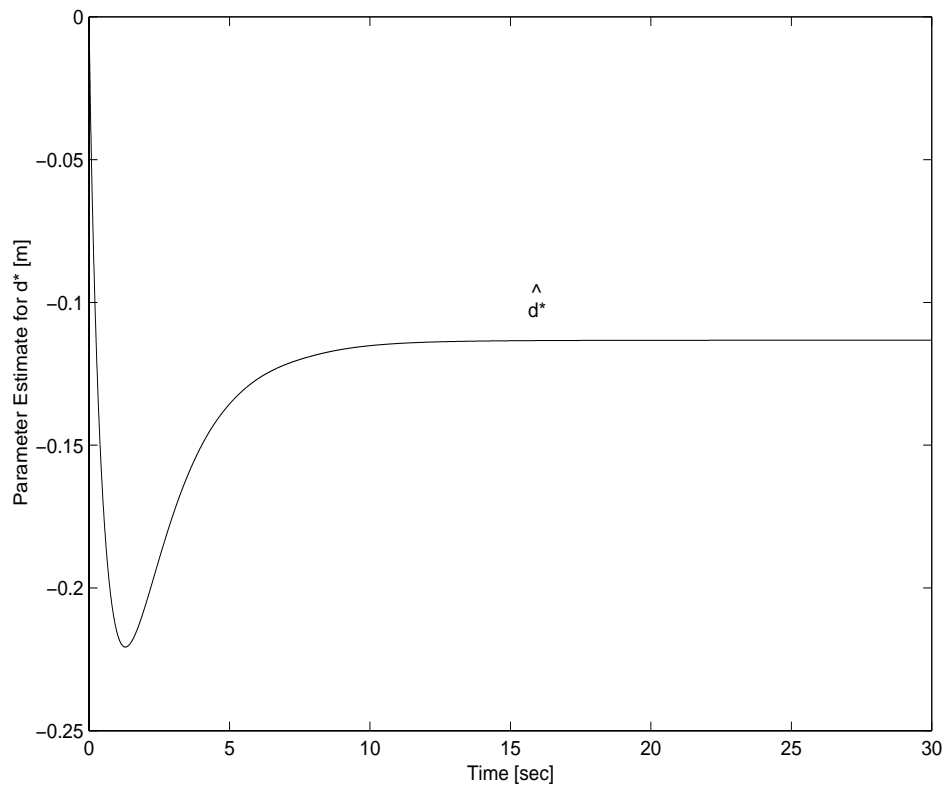


Figure 3: Parameter Estimate for \hat{d}^*

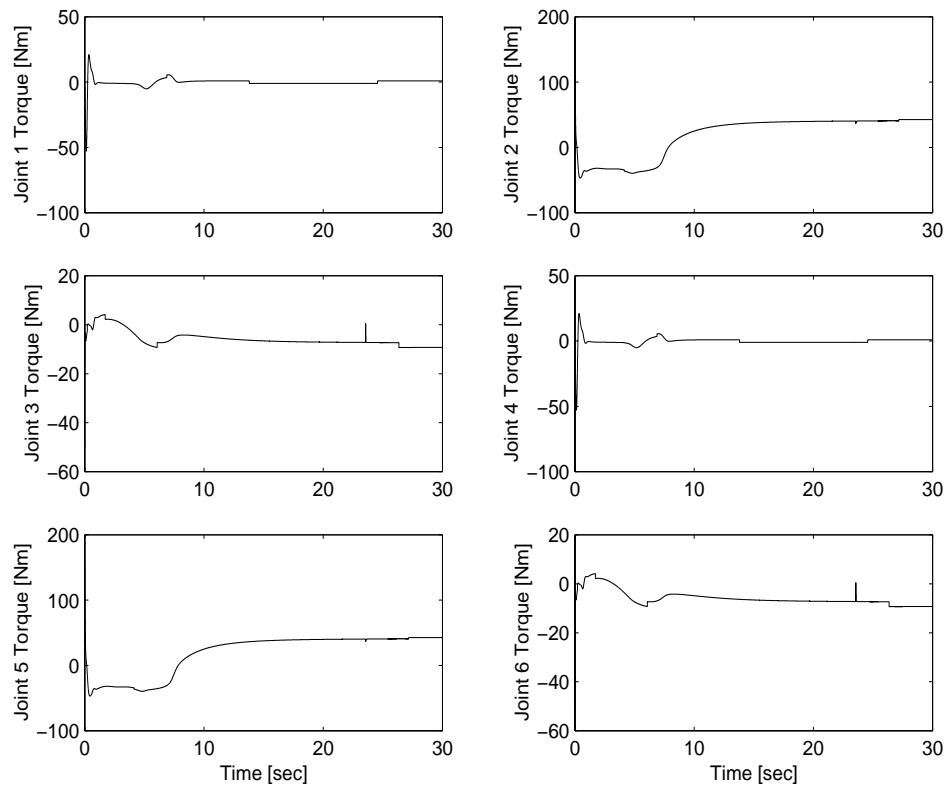


Figure 4: Control Torque Input